

# New Fixed Point Theorem for Expansive Maps on a Two – Metric Space

#### Sami Abdullah Abed

College of Administration and Economics-University of Diyala

samiaabed@uodiyala.edu.iq

Received: 10 February 2023 Accepted: 25 June 2023

DOI: https://doi.org/10.24237/ASJ.02.01.759A

## **Abstract**

In this paper new theorems a bout fixed point are given for applications in 2- metric space. The common fixed points of two operators exhibit a shared periodicity in their occurrences. The theorem demonstrates that, certain conditions, there exists a specific pattern or sequence of operators where the fixed points exhibit a common periodicity.

**Keyword:** Two – Metric Space, fixed point, applications in 2- metric space, theorems in Two – Metric Space

نظريات جديدة للنقطة الثابتة لتطبيقات معرفة على الفضاء المتري الثنائى

سامي عبدلله عبد

كلية الادارة والاقتصاد - جامعة ديالي

## الخلاصة

هدفت الدراسة لعرض نظريات جديدة ، للتطبيقات نقطة ثابتة في 2- الفضاء مترية. مثل النقاط الثابتة الدورية المشتركة بين عمليتين ، ، او سلسلة من العمليات تحت شروط نظريات موضوع البحث.

الكلمات مفتاحية: الفضاء المتري الثنائي ، النقطة الثابتة ، تطبيقات في الفضاء المتري الثنائي، نظريات في الفضاء المتري الثنائي



## **Introduction**

A metric space (X, d) is familiar for B.Sc. Students in mathematic where the metric function d is not unique and if  $(X, d_1)$  and  $(X, d_2)$  are matrices spaces with X as finite dimensional than  $(X, d_2)$  and  $(X, d_2)$  are equivalent. In initial value problem we use the complete metric space (X, d) where X consists of the solution and d as contraction to get unique fixed point that is to get unique solution.

There are some generalization for a metric space and the fixed point , such as D-metric space, complex value metric space , G.metric space and 2-metric space[4,19,525,26,27,28,29,30], 2-metric space and ordinary metric are not topologically equivalent. Therefor the relationship between the obtained results is not easy in 2-metric space and metric space. Also the themes of fixed point between there the kinds of metric spaces are not related easily in general [4, 19, 27].

Extensive research has been carried out in the field. Duo 1963 and Gahler were the first to work in this space. A number of applications such as game theory, medicine, economic etc. The fixed point theorem in mathematics can be considered as a consequence for studing functions or operators on a spaces. A point  $x_0$  is called fixed point for a function f(x) if  $f(x_0) = x_0$ . Remember that functions can have no or one or finite or infinite a fixed point [1]. Such that  $f(x) = x^2 + 1$ ,  $f(x) = \sin x$ , f(x),  $x^2$ , and f(x) = x respectively, Banach and Brauer are the pioneers of this field. One can use fixed point theorem for proving the uniqueness of the set. of a given initial value problem under certain conditions. That it is used frequently in many fields such as dynamical system, physics, energy, etc. [2, 3]

### **Metric Space**

#### **Definition 1:**

2- Metric space [7]: Suppose X is non empty set and suppose d:  $X * X \rightarrow R$  satisfies the following conditions :

1. For a pair of points  $x, y \in X$  there exists a point  $z \in X$  such that  $d(x, y, z) \neq 0$ .



- 2. For each  $x, y, z \in X$  then d(x, y, z) = d(x, z, y) = d(y, x, z) = d(y, z, x) = d(z, x, y) = d(z, y, x)
- 3. For all x, y, z, t  $\in$  X then the inequality  $d(x, y, z) \le d(x, y, t) + d(x, y, t) + d(y, z, t)$  holds
- 4. For all  $x, y, z \in X$  then d(x, y, z) = 0 iff

$$x = y = z$$

### **Definition 2**[1]:

Convergence in 2 – metric space: Suppose  $(x_n)$  is a sequences in a 2- metric space (X, d) then we say that  $(x_n)$  converges to  $x \in X$  if satisfies the following condition: For all  $a \in X$  then  $\lim_{n \to \infty} d(x_n, x, a) = 0$ .

## **Definition 3**[6]:

Cauchy sequence in 2 – metric space ( $x_n$ ) is cauchy sequence in 2 – metric space if satisfies the following conditions:

for all:  $a \in X$ ,  $n, m \in N$  then  $\lim_{n,m \to \infty} d(x_n, x_m, a) = 0$ 

## Theorems for fixed points in 2 – metric space

```
Theorem 1 [21]:
```

Suppose X is a complete 2 – metric space and suppose  $f: X \to X$  satisfy for all:

x, y, a ∈ X ,

d(f(x), f(y), a)

$$\leq \alpha[d(x, f(x), a) + d(y, f(y), a)] + \beta d(x, y, a)$$

+  $\gamma \max\{d(x, f(y), a), d(y, f(x), a)\}$ .

s.t.  $\alpha,\beta,\gamma\geq 0$ ,  $2\alpha+\beta+2\gamma<1$  then the function f has a fixed point z and  $\underset{n\rightarrow\infty}{\lim}f^n(x_0)=z$ ,  $\forall\;x_0\in X$ .

**Theorem 2** [12]:

Suppose X is complete 2- metric space and suppose  $f_1$  and  $f_2$  are two mappings in X then for all  $x, y, a \in X$ :



 $\begin{aligned} &d(f_1(x), f_2(y), a) \leq a_1 d(x, f_1(x), a) + a_2 d(y, f_2(y), a) + a_3 d(x, f_2(y), a) + \\ &a_4 d(y, f_1(x), a) + a_5 d(x, y, a) \\ &\text{such that } a_{1,a_2, a_3, a_4} \text{ and } a_5, \quad \text{are non-negative numbers satisfy } \sum_{i=1}^5 a_i < 1 \\ &\text{and } (a_1 - a_2), (a_3 - a_4) \geq 0 \text{ then } f_1 \text{ and } f_2 \text{ have a common fixed point .} \end{aligned}$ 

### **Theorem 3 [21]**:

Suppose (X, d) is complete 2-metric space and suppose f is continuous mapping from X s. t. f: X  $\rightarrow$  X and satisfy the following conditions  $d^{2}(fx, fy, a) \leq \alpha d(x, fx, a) d(y, fy, a) + \beta d(x, fx, a) d(y, fx, a) + \gamma d(y, fy, a) d(y, fx, a) + \delta d(x, fy, a) d(y, fx, a),$ 

for all x, y,  $a \in X$  and  $\alpha, \beta, \gamma, \delta \ge 0$  and  $max(\alpha, \delta) < 1$  then f has fixed point in X.

#### **Theorem 4**[21]:

Suppose (X, d) is complete 2-metric space and suppose f, T are two continuous identical mappings from X and satisfy the following conditions:

- 1.  $fT = Tf; f(X) \subset T(X)$
- 2.  $d^{2}(fx, fy, a) \leq \alpha d(Tx, fx, a)d(Ty, fy, a) + \beta d(Tx, fx, a)d(Ty, fx, a) +$  $\gamma d(Ty, fy, a)d(Ty, fx, a) + \delta d(Tx, fy, a)d(Ty, fx, a).$

For all x, y,  $a \in X$  and  $\alpha$ ,  $\beta$ ,  $\gamma$ ,  $\delta \ge 0$  with max $(\alpha, \delta) < 1$  then f, T has a common fixed point in X.

#### **Theorem 5**[21]:

Suppose (X, d) complete 2-metric space and suppose E, T, F continuous functional from X and satisfy the following conditions:

- 1. ET = TE; FT = TF; E(X)  $\subset$  T(X); F(X)  $\subset$  T(X)
- 2.  $d^{2}(Ex, Fy, a) \leq \alpha d(Tx, Ex, a)d(Ty, Fy, a) + \beta d(Tx, Ex, a)d(Ty, Ex, a)ET + \gamma d(Ty, Fy, a)d(Ty, Ex, a) + \delta d(Tx, Fy, a)d(Ty, Ex, a)$



For all  $x, y, a \in X$  and  $\alpha, \beta, \gamma, \delta \ge 0$  with  $\max(\alpha, \delta) < 1$  then E, T, F have a commu fixed point in X.

Convergence theorems of sequences of mappings in a 2-metric space and their fixed points:

#### **Theorem 1 [18]**

Suppose X is complete 2-metric space and d is continuous and suppose

 $\{f_n\}$  sequence of mappings. Defined by  $f_n: X \to x$  and satisfy the following conditions:

$$d(f(x), f(y), a) \le \alpha[d(x, f(x), a) + d(y, f(y), a)] + \beta d(x, y, a)$$

+  $\gamma \max\{d(x, f(y), a), d(y, f(x), a)\}$ 

For  $n \in N$  and the numbers  $\alpha, \beta, \gamma \in \mathbb{R}^+$  also  $\{f_n\}$  converges point wise to f, then f has a fixed point z and such that  $z_n \to z$  then  $z_n$  is the fixed point of  $f_n$ .

#### **Theorem 2 [21]**

Suppose X complete 2-metric space and suppose  $\{f_n\}$  sequence of functions  $f_n: X \to X$  has fixed point  $z_n$  with the following conditions:

$$\begin{aligned} d(f(x), f(y), a) &\leq \alpha [d(x, f(x), a) + d(y, f(y), a)] + \beta d(x, y, a) \\ &+ \gamma max \{ d(x, f(y), a), d(y, f(x), a) \} \end{aligned}$$

has fixed points z and such that  $f_n \rightarrow f$  there regularly  $z_n \rightarrow z.$ 

#### Main Results

Through the following five theorems we prove the existance of fixed points of operators defend on 2- metric spaces and also a common fixed point for operators under certain conditions as shown in these theorems

#### Theorem 1

Suppose X is complete 2-metric space and suppose  $T: X \rightarrow X$  satisfies:

$$d(Tx, Ty, a) \ge \sqrt{d(x, Tx, a)d(y, Ty, a)}$$

For all, y, a  $\,\in X\,$  , then T has periodic point and T continuous functional.

### **Proof:**

Define a sequence  $(x_n)$  from X such that  $x_n = T^n x_0$ 

for some value  $x_0$  suppose  $x_n \neq x_m$  whatever m, n then:

 $d(x_n, x_{n+1}, a) = d(Tx_{n-1}, Tx_n, a) \ge \sqrt{d(x_{n-1}, Tx_{n-1}, a)d(x_n, Tx_n, a)}$ 



 $=\sqrt{d(x_{n-1}, x_n, a)d(x_n, x_{n+1}, a)}$ 

or  $d(x_n, x_{n+1}, a) \ge d(x_{n-1}, x_n, a)$ .

Similarly:  $d(x_{n-1}, x_n, a) \ge d(x_{n-2}, x_{n-1}, a)$  and so we find:

$$d(x_n, x_{n+1}, a) \ge d(x_{n-1}, x_n, a) \ge \cdots \ge d(x_0, x_1, a)$$

and so for all positive numbers r, n we find:

$$d(x_n, x_{n+r}, a) \ge \sqrt{d(x_{n-1}, x_n, a)d(x_{n+r-1}, x_{n+r}, a)}$$
$$\ge d(x_0, x_1, a) > 0$$

That is  $d(x_n, x_{n+r}, a) \ge 0$ 

This shows that the sequence  $(x_n)$  is not convergent and this is a contradiction so  $x_n \neq x_m$  is not for all values of m, n so we have  $x_n = x_{n+r}$  for some values of  $n \ge 0, r \ge 1$  then  $x_n = T^r x_n$ .

Now let's say n is the smallest non-negative integer such that  $x_n = x_{n+r}$  so we'll choose the smallest number r, let's say  $n \ge 1$  then the sequence  $x_0, x_1, \dots, x_{n+r-1}$  consists of different points.

Now we have:

$$0 = d(x_n, x_{n+r}, a) \ge \sqrt{d(x_n, x_{n-1}, a)d(x_{n+r}, x_{n+r-1}, a)}$$
$$\ge d(x_1, x_0, a) \ge 0$$

It is axiomatic that n = 0 so  $x_0$  is a periodic point of T.

Let's say  $T_x = T_y$  for some  $x \neq y$  thus:

$$0 = d(Tx, Ty, a) \ge \sqrt{d(x, Tx, a)d(y, Ty, a)}$$

This gives that  $x = T_x$  or  $y = T_y$  and since y is periodic we have  $T^m y = y$  for some values of > 0, now for  $x = T_x$  and  $y = T^m y = T^{m-1}T_y = T^{m-1}T_x = x$  that is x = y and this is a contradiction.

Similarly,  $T_y = y$  leads to contradiction, which means that T is a discrete implementation.

#### Theorem 2:

Suppose S, T: X  $\rightarrow$  Xare continuous mappings on a complete 2-metric space X in which:

$$d(Sx, Ty, a) < \sqrt{d(x, Sx, a)d(y, Ty, a)}$$



So for all x, y,  $a \in X$  and  $x \neq y \neq a$  then S and T have a common fixed point and X is a singular space.

#### **Proof:**

Define the sequence  $(x_n)$  of X so that  $x_{2n+1} = Sx_{2n}, x_{2n} = Tx_{2n-1}$  so X is a compact space so  $(x_n)$  has partial chains  $x_{nk}$  such that  $x_{nk} \to x$  in X for some x of X. Now from the continuation S, T we have:

$$x = \lim_{k \to \infty} x_{n_{2k}} = \lim_{k \to \infty} Tx_{n_{2k-1}} = T\left(\lim_{k \to \infty} x_{n_{2k-1}}\right) = Tx \text{ or } x = Tx$$

Similarly  $x = S_x$ .

We will now prove that X is singular so let's put  $y \neq x$  of X then for each a from X we have :

$$d(x, Ty, a) = d(Sx, Ty, a) < \sqrt{d(x, Sx, a)d(y, Ty, a)} = 0$$

Or  $d(x, T_y, a) < 0$  for each a of X which is not possible therefore x = y

#### Theorem 3:

Assuming X is a 2-metric space and assuming  $T: X \to X$ , such that:

$$d(Tx, Ty, a) \ge \frac{d^2(Tx, x, a) + d^2(Ty, y, a)}{d(Tx, x, a) + d(Ty, y, a)}$$

and that for all  $a \in X$  and  $d(T_x, x, a) + d(T_y, y, a) \neq 0$  then every point x of X is a fixed point of T.

### **Proof:**

Assuming x is some point of X then for each  $\in$  X :

$$0 = d(Tx, x, a) \ge \frac{d^2(Tx, x, a) + d^2(Tx, x, a)}{d(Tx, x, a) + d(Tx, x, a)} = d(Tx, x, a)$$

That is, d(Tx, x, a) = 0 for each  $a \in X$  or Tx = x.

### Theorem 4:

Suppose  $S_n, T_n: X \to X$  are a sequences of mappings such that:

$$d(S_m x, T_n y, a) \le h \sqrt{d(S_m x, x, a) d(T_n y, y, a)}$$

This is for all x, y,  $a \in X$  and 0 < h < 1 then for all values of m, n for which  $S_n$  and  $T_n$  have a common fixed point.

**Proof:** Let's define the sequence  $(x_n)$  of X, so that  $x_{2n+1} = S_{n+1}x_{2n}, x_{2n} = T_nx_{2n-1}$ .



If  $x_{2n} \neq x_{2n+1}$  then for each a of X we have:

$$\begin{split} d(x_{2n+1}, x_{2n}, a) &= d(S_{n+1}x_{2n}, T_n x_{2n-1}, a) \\ &\leq h \sqrt{d(S_{n+1}x_{2n}, x_{2n}, a)d(T_n x_{2n-1}, x_{2n-1}, a)} \\ &= h \sqrt{d(x_{2n+1}, x_{2n}, a)d(x_{2n}, x_{2n-1}, a)} \\ \end{split}$$
That is:  $d(x_{2n+1}, x_{2n}, a) &\leq \rho d(x_{2n}, x_{2n-1}, a); \ \rho = h^2 < 1$ Similarly:  $d(x_{2n}, x_{2n-1}, a) \leq \rho d(x_{2n-1}, x_{2n-2}, a); \ \rho = h^2 < 1$ In general :  $d(x_{n+1}, x_n, a) \leq \rho d(x_n, x_{n-1}, a)$ or :  $d(x_{n+1}, x_n, a) \leq \rho^n d(x_1, x_0, a)$ Then  $n \rightarrow \infty$  find  $\lim_{n \rightarrow \infty} d(x_{n+1}, x_n, a) = 0$  so that  $\rho < 1$ . It is easy to prove that  $(x_n)$  is the Cauchy sequence in X and that  $(x_n) \rightarrow x; x \in X$ . Now let's take  $d(x_{2n+1}, T_m x, a) = d(S_{n+1}x_{2n}, T_m x, a)$   $&\leq h \sqrt{d(S_{n+1}x_{2n}, x_{2n}, a)d(T_m x, x, a)}$  $&= \sqrt{d(x_{2n+1}, x_{2n}, a)d(T_m x, x, a)}$ 

When  $n \to \infty$  we find  $d(x, T_m x, a)$  or  $x \in T_m x$  for all values of m and similarly  $x \in S_m x$  this means that  $S_n$ ,  $T_n$  has a common fixed point.

#### Theorem 5:

Assuming that X is a 2-metric space with two distance functions e, d if X satisfy the conditions:

- 1. X is a complete metric space with the distance e.
- 2.  $e(x, y, a) \le d(x, y, a)$

3. S,  $T_n: X \to X$  and S continuing and checking  $(Sx, T_ny, a) \le \sqrt{d(Sx, x, a)d(T_ny, y, a)}$ So for all x, y,  $a \in X$  and 0 < h < 1, then for all,S and  $T_n$  has a common fixed point.

**Proof:** Let us know the sequence  $(x_n)$  from X, so that  $x_{2n+1} = Sx_{2n}, x_{2n} = T_n x_{2n-1}$  then according to the theorem (4),  $(x_n)$  will be a Cauchy sequence with a distance function d and only (2) in  $(x_n)$  is a Cauchy sequence with a space function e as well, so  $(x_n) \rightarrow x$ ;  $x \in X$ . From the continuum of S we have  $x = S_x$ .

Put d(x, T<sub>n</sub>x, a) = d(Sx, T<sub>n</sub>x, a) 
$$\leq h\sqrt{d(Sx, x, a)d(T_nx, x, a)}$$
  
= d(x, T<sub>n</sub>x, a) = 0



That is for every  $a \in X$  or  $x = T_n x$  for every n, so S,  $T_n$  have a common fixed point.

## **Conclusion**

From the proved five theorems 2.4.1..... 2.4.5 we conclude when the 2-metric space is complete then the operator under certain condition is continuous and each point is periodics. If two operators are continuous and satisfy a given condition then they have common fixed point. Similarly for a sequencesal operators.

## **References**

- 1. M. Abramowiz, I. A. Stegun, eds. Hand book of Mathematical Functions, (Dover Publications, New York, 1965)
- 2. Alexander, Diagonally implicit Runge-Kutta methods for stiff ODEs, SIAMJ. Numer. Anal., 14(6), 1006-1021(1977)
- **3.** constantinides, Numerical Methods for Chemical Engineers with Matlab Applications, (New Jersey, 1999)
- 4. A. C. Simpson, Fixed points and lines in 2-metric spaces, Adv Math., 229, 668-600(2012)
- W. F. Ames, Numerical Methods for Partial Differential Equations, 3<sup>rd</sup> ed., (Academic, Inc., 1992)
- 6. O. Axelsson, A class of A-Stable Methods, BIT., 9, 185-199(1969)
- 7. M. Bakker, Analytical aspects of a minimax Problem, (Mathematical center, Amsterdam, 1971)
- 8. J. C. Butcher, Implicit Runge Kutta Processes, Math. Comp, 18, 50-64(1964)
- J. C. Butcher, Z. Jackiewic, Implementation of Diagonally Implicit Multistage Integration Methods for Ordinary Differential Equations, SIAM J. Numer. Anal., 34(6), 2119-2141(1997)
- 10. J. C. Butcher, Z. Jackiewic, Areliable Error Estimation For Diagonally Implicit Multistage integration Methods, BIT, 41(4), 656-665(2001)



- **11.** J. C. Butcher, W. N. Wright, A transformation relating explicit and diagonallyimplicit general linear methods, J. APPL. Numer. Math, 44, 313-327(2003)
- 12. J. C. Butcher, Z. Jackiewic, Construction of high order diagonally implicit multistage integration methods for ordinary differential equations, J. APPL. Numer. Math, 27, 1-12 (1998)
- 13. J. C. Butcher, A stability Property of implicit Runge-Kutta methods, BIT, 15, 358-361 (1975)
- 14. K. Burrage, F. H. Chipman, The Stability Properties of Singly -implicit general Linear Methods, IMA J. Numer. Anal, 5, 287-295(1985)
- 15. K. Burrage, J. C. Butcher, Stability criteria for implicit Runge-Kutta Methods, SIMA J. Numer. Anal, 16(1), 46-57(1979)
- **16.** G. J. Cooper, J. C. Butcher, An Iteration scheme for implicit Runge-Kutta methods,IMA J. Numer. Anal, 3, 127-140(1983)
- 17. G. Dahlquist, A. Biorck, Numerical Methods, (Prentice-Hall, Inc., 1987)
- **18.** K. Dekker, J. C. Verwer, Stability of Runge-Kutta methods for stiff non-linear differential equations, Elsevier Science Publishers B. V, (1984)
- 19. B. Deshpande, S. Chouhan, Common fixed point theorems for hybrid pairs of mappings with some weaker conditions in 2-metric spaces, Fasc. Math. 46, 37-55(2011)
- 20. B. I. Ehle, One Pade Approximations for the exponential function and A-stable methods for the solution of initial value problems, Univ of waterloo, Dept. Applied Analysis and computer science, Research Rep. No. CSRR 2010, (1969)
- **21.** R.Frank, G. Kirlinger, A Note on convergence concepts for stiff problems, J. computing, 44, 197-208(1990)
- **22.** R. Frank, J. Schneld, W. Christopher, Order results for implicit Runge-Kutta methods applied to stiff systems, SIAM J. Numer. Anal., 22(3), 515-534(1985)
- 23. R. Frank, J. Schneld, W. Christopher, Stability properties of implicit Runge-Kutta methods, SIAM J. Numer. Anal., 22(3), 497-514(1985)



- 24. R. Frank, J. Schneld, W. Christopher, The concept of B-Convergence, SIAM J. Numer. Anal., 18(5), 753-779(1981)
- 25. Y. Feng, W. Mao, The equivalence of cone metric spaces and metric spaces, Fixed Point Theory, 11(2), 259-264(2010)
- **26.** L. G.Huang, X. Zhang, Cone metric spaces and fixed point theorems of contractive mappings, J. Math. Anal. Appl. 332, 1468-1476(2007)
- 27. K. Iseki, Fixed point theorems in 2-metric spaces Math Sem, Notes Kobe Univ., 3, 133-136(1975)
- **28.** M. Jleli, B. Samet, Remarks on G-metric spaces and fixed point theorems, Foxed Point Theory Appl. 2012, Article ID-201(2012)
- 29. Z. Mustafa, B. Sims, Some remarks concerning D-metric spaces, In: Proceedings of the International Conferences on Fixed Point Theory and Applications, Valencia, Spain, 189-198 (2001)
- **30.** Z. Mustafa, B. Sims, A new approach to generalized metric spaces, J Nonlinear Convex Anal, 7(2), 289-247(2006)